

Chapter 7: Complex numbers

Quadratic equation:

$$a\lambda^2 + b\lambda + c = 0 ,$$

with roots

$$\lambda_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{-b \pm \sqrt{D}}{2a} \quad \text{where } D = b^2 - 4ac$$

What if $D < 0$? Define:

$$i^2 = -1 \quad \text{or equivalently} \quad i = \sqrt{-1}$$

Solve $\lambda^2 = -3$ by using $i^2 = -1$: $\lambda^2 = i^2 \times 3$ or $\lambda_{1,2} = \pm i\sqrt{3}$

So if $D < 0$ write:

$$\lambda_{1,2} = \frac{-b \pm i\sqrt{-D}}{2a}$$

Solve the equation $\lambda^2 + 2\lambda + 10 = 0$:

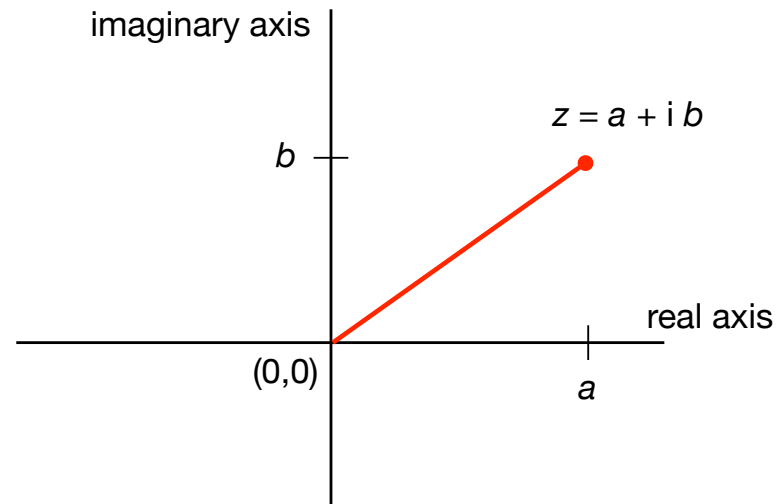
$$\lambda_{1,2} = \frac{-2 \pm \sqrt{4 - 4 \times 10}}{2} = \frac{-2 \pm \sqrt{-36}}{2} = \frac{-2 \pm 6i}{2}$$

In other words, $\lambda_1 = -1 + 3i$ and $\lambda_2 = -1 - 3i$.

A complex number z is written as $z = \alpha + i\beta$, where α is called the real part and $i\beta$ is called the imaginary part.

These two solutions are complex conjugates: $z_1 = a + ib$ and $z_2 = a - ib$

Argand diagram: complex number as a vector:



Addition of two complex numbers: adding their real parts, and add their imaginary parts.

With $z_1 = 3 + 10i$ and $z_2 = -5 + 4i$:

$$z_1 + z_2 = (3 + 10i) + (-5 + 4i) = 3 - 5 + 10i + 4i = -2 + 14i .$$

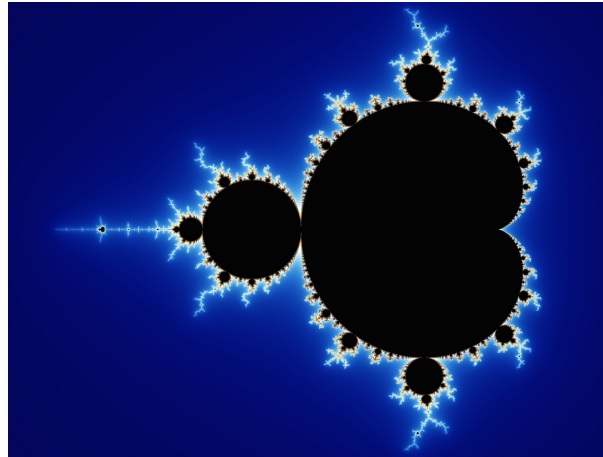
Multiplication works like $(a + bx)(c + dx)$:

$$\begin{aligned}z_1 \times z_2 &= (3 + 10i)(-5 + 4i) \\&= 3(-5) + 3 \times 4i + 10i(-5) + 10i4i \\&= -15 + 12i - 50i + 40i^2 \\&= -15 - 38i - 40 \\&= -55 - 38i .\end{aligned}$$

Note: $(a + ib)(a - ib) = a^2 + b^2$

If $z = a + ib$, its modulus $|z| = \sqrt{a^2 + b^2}$ (magnitude, length vector).

Hence $z\bar{z} = |z|^2$. (Used for division).



Mandelbrot set: $z_i = z_{i-1}^2 + z_0$, where $z_1 = z_0 = a + bi$ is a point in the Argand diagram.

Black points remain bounded, colored points keep growing. The color indicates the number of iterations $i = 1, 2, \dots, n$ required to reach a size of z_n .

Start with $z_0 = 0.5$: $0.5, 0.5^2 + 0.5 = 0.75, 0.75^2 + 0.5, \dots$

Linear ODEs

$$\begin{cases} dx/dt = ax + by \\ dy/dt = cx + dy \end{cases} \quad \text{with} \quad \lambda_{1,2} = \frac{\text{tr} \pm \sqrt{D}}{2} \quad \text{and} \quad \begin{cases} (a - \lambda_i)x + by = 0 \\ cx + (d - \lambda_i)y = 0 \end{cases}$$

$$\lambda_{1,2} = \frac{\text{tr} \pm i\sqrt{-D}}{2} \quad \text{or} \quad \lambda_{1,2} = \alpha \pm i\beta$$

$$\begin{aligned} \vec{v}_1 &= k \begin{pmatrix} -b \\ a - \lambda_1 \end{pmatrix} = k \begin{pmatrix} -b \\ a - (\alpha + i\beta) \end{pmatrix} \\ &= k \begin{pmatrix} -b \\ a - \alpha \end{pmatrix} - ik \begin{pmatrix} 0 \\ \beta \end{pmatrix} = k\vec{w}_R - ik\vec{w}_I \end{aligned}$$

where $\vec{w}_R = \begin{pmatrix} -b \\ a - \alpha \end{pmatrix}$ and $\vec{w}_I = \begin{pmatrix} 0 \\ \beta \end{pmatrix}$

Similarly

$$\vec{v}_2 = k \begin{pmatrix} -b \\ a - \lambda_2 \end{pmatrix} = k \begin{pmatrix} -b \\ a - (\alpha - i\beta) \end{pmatrix} = k\vec{w}_R + ik\vec{w}_I$$

General solution:

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = C_1(\vec{w}_R - i\vec{w}_I)e^{(\alpha+i\beta)t} + C_2(\vec{w}_R + i\vec{w}_I)e^{(\alpha-i\beta)t}$$

where the constants k are absorbed into C_1 and C_2 .

Euler's formula:

$$e^{ix} = \cos x + i \sin x \quad \text{or} \quad e^{-ix} = \cos x - i \sin x$$

hence

$$e^{(\alpha+i\beta)t} = e^{\alpha t} e^{i\beta t} = e^{\alpha t} (\cos \beta t + i \sin \beta t)$$

From

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = C_1(\vec{w}_R - i\vec{w}_I)e^{(\alpha+i\beta)t} + C_2(\vec{w}_R + i\vec{w}_I)e^{(\alpha-i\beta)t}$$

we obtain

$$\begin{aligned} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} &= C_1(\vec{w}_R - i\vec{w}_I)e^{\alpha t}(\cos \beta t + i \sin \beta t) \\ &+ C_2(\vec{w}_R + i\vec{w}_I)e^{\alpha t}(\cos \beta t - i \sin \beta t) \\ &= e^{\alpha t}[C_1(\vec{w}_R - i\vec{w}_I)(\cos \beta t + i \sin \beta t) \\ &+ C_2(\vec{w}_R + i\vec{w}_I)(\cos \beta t - i \sin \beta t)] . \end{aligned}$$

which dies out whenever $\alpha = \text{tr}/2 < 0$.

Initial condition where $t = 0$, $e^{\alpha t} = 1$, $\cos \beta t = 1$ and $i \sin \beta t = 0$,

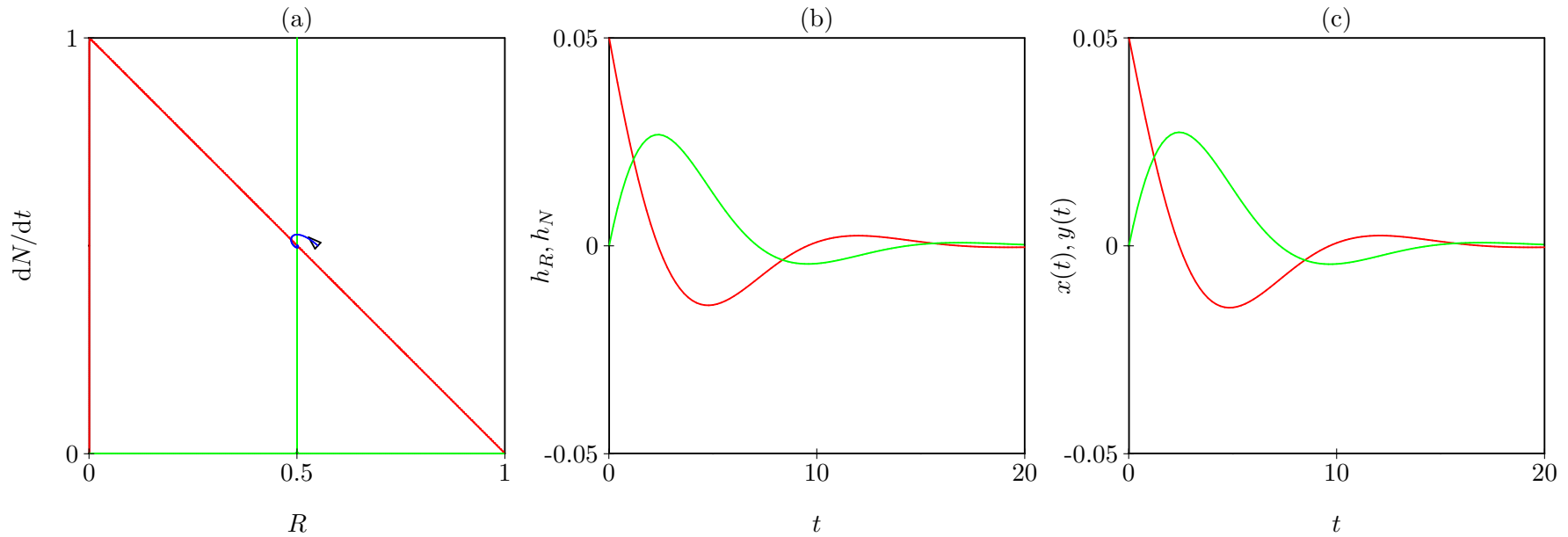
$$\begin{aligned} \begin{pmatrix} x(0) \\ y(0) \end{pmatrix} &= C_1(\vec{w}_R - i\vec{w}_I) + C_2(\vec{w}_R + i\vec{w}_I) \\ &= \vec{w}_R(C_1 + C_2) + i\vec{w}_I(C_2 - C_1), \quad \text{or} \end{aligned}$$

$$x(0) = -b(C_1 + C_2) \quad \text{and} \quad y(0) = (a - \alpha)(C_1 + C_2) + i\beta(C_2 - C_1)$$

from which we solve the complex pair C_1 and C_2 .

Note that $C_1 + C_2$ should be real, whereas $C_2 - C_1$ should be an imaginary number.

Lotka-Volterra model



$$\frac{dR}{dt} = aR - bR^2 - cRN, \quad \frac{dN}{dt} = dRN - eN$$

With $a = b = c = d = 1, e = 0.5, \bar{R} = 0.5$ and $\bar{N} = 0.5$,
and $h_R = 0.05$ and $h_N = 0$

$$J = \begin{pmatrix} -\frac{be}{d} & -\frac{ce}{d} \\ \frac{da-eb}{c} & 0 \end{pmatrix} = \begin{pmatrix} -b\bar{R} & -c\bar{R} \\ d\bar{N} & 0 \end{pmatrix} .$$

For $a = b = c = d = 1$ and $e = 0.5$, $\bar{R} = 0.5$ and $\bar{N} = 0.5$, and

$$J = \begin{pmatrix} -0.5 & -0.5 \\ 0.5 & 0 \end{pmatrix} \quad \text{with} \quad D = -0.75$$

implying that

$$\lambda_{1,2} = \frac{\text{tr} \pm i\sqrt{-D}}{2} \quad \text{or} \quad \lambda_{1,2} = \frac{-0.5 \pm i\sqrt{0.75}}{2} = -0.25 \pm i 0.43 .$$

Hence $\alpha = -0.25$ and $\beta = 0.43$, the nontrivial state is stable, has a return time of $-1/\alpha = 4$, and a wave length proportional to $1/\beta$.

$$\vec{v}_1 = \begin{pmatrix} 0.5 \\ -0.25 - i0.43 \end{pmatrix} \quad \text{and} \quad \vec{v}_2 = \begin{pmatrix} 0.5 \\ -0.25 + i0.43 \end{pmatrix} .$$

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = e^{-0.25t} [C_1 \vec{v}_1 (\cos 0.43t + i \sin 0.43t) + C_2 \vec{v}_2 (\cos 0.43t - i \sin 0.43t)]$$

$$x(t) = e^{-0.25t} 0.5[(C_1 + C_2) \cos 0.43t + (C_1 - C_2)i \sin 0.43t]$$

$$y(t) = \dots$$

Using the initial condition, where $t = 0$, $e^{-0.25t} = 1$, $\cos 0.43t = 1$, and $\sin 0.43t = 0$, the linearized solution $x(t)$ simplifies into

$$x(0) = 0.05 = 0.5(C_1 + C_2) \quad , \quad \text{and hence} \quad C_1 + C_2 = 0.1 .$$

$y(t)$ simplifies into

$$0 = i0.43(C_2 - C_1) - 0.25(C_1 + C_2) \quad \Leftrightarrow \quad C_2 - C_1 = -i0.058 .$$

We find that $C_1 = 0.05 + i0.029$ and $C_2 = 0.05 - i0.029$.

Substituting these constants into $x(t)$ gives

$$\begin{aligned} x(t) &= e^{-0.25t} 0.5[0.1 \cos 0.43t + i^2 0.058 \sin 0.43t] , \\ &= e^{-0.25t} [0.05 \cos 0.43t - 0.029 \sin 0.43t] \end{aligned}$$

and in $y(t)$

$$y(t) = e^{-0.25t} 0.058 \sin 0.43t,$$

Both are perfectly real.

The end

